| Name: | Arr: |
|-------|------|

Messing Around with Sensors and Switches Worksheet

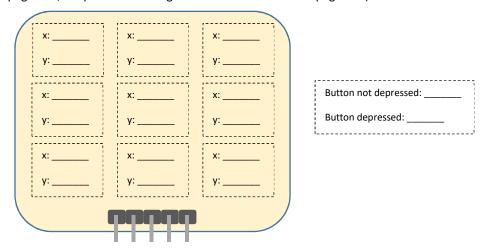
Record the digital output values and other observations of all the sensors mentioned and covered in Volume Two.

You may want to review the following sections in the textbooks:

- Voltage divider board (VDB) theory & analytics (Chapter 21 on pp 808 812)
- Pull-up resistor and VDB theory (Chapter 21 on pp 819 821)

Sensors Covered in the Textbook

• 2-axis Joystick (Chapter 21 on page 798; Chapter 22 Challenge Problem with button on page 878)



8-Button Board using Pull-up Resistors (Chapter 22 on pp 859 – 862)

| Using Internal Pull-up Resistors | | | | | | |
|----------------------------------|----------------------|--|--|--|--|--|
| Button(s) not depressed: | Button(s) depressed: | | | | | |

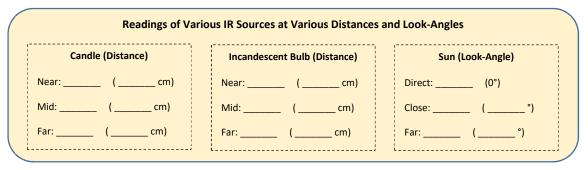
Battery Level Meter (VDB/Fixed Resistor or Commercial Plug-in Meter) (Chapter 21 on pp 813 – 814)

| Robot Battery Pack Voltage | | | | | |
|----------------------------|---|-----------------|--|--|--|
| Current: | V | Post Charging:V | | | |

• **Hygrometer** (*Chapter 21* on pp 787 – 793)



• IR (Flame) Detector (passive IR) (Chapter 21 on pp 794-795)



| | [] | · · · · · · · · · · · · · · · · · · · | | |
|--------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------|-----------------------------------------|--|
| | Line Colors (Left Sensor) | Line Colors (Right Sensor) | | |
| | White: | White: | | |
| | Light Gray: | Light Gray: | | |
| | Dark Gray: | Dark Gray: | | |
| | Black: | Black: | | |
| lagnetic Field (Hall-Effect) Se | nsor (Chapter 21 on pp 799 – 8 No Magnetic Field | 803; and curve fitting on pp 807 Present: | – 808) | |
| Hall-Effect North Pole (Distance) | Readings of a <u>Weak</u> Magnetic Figure South Pole (Distance) | eld at Various Distances and Incide North Pole (Incidence Angle) | nce Angles South Pole (Incidence Angle) | |
| Near: (cm) | Near: (cm) | Perpendicular: (90°) | Perpendicular: (90°) | |
| Mid: (cm) | Mid: (cm) | Angled: (45 °) | Angled: (45 °) | |
| Far: (cm) | Far: (cm) | Parallel: (0 °) | Parallel: (0 °) | |
| | | | | |
| Hall-Effect | Readings of a <u>Strong</u> Magnetic Fi | ield at Various Distances and Incide | ence Angles | |
| North Pole (Distance) | South Pole (Distance) | North Pole (Incidence Angle) | South Pole (Incidence Angle) | |
| Near: (cm) | Near: (cm) | Perpendicular: (90°) | Perpendicular: (90°) | |
| Mid: (cm) | Mid: (cm) | Angled: (45 °) | Angled: (45 °) | |
| Far: (cm) | Far: (cm) | Parallel: (0 °) | Parallel: (0 °) | |
| В | on pp 854 – 857; and using pul Using External Resistor or VDB utton not depressed: | Using Internal Pull-up Resistor Button not depressed: | | |
| L | utton depressed: | Button depressed: | | |
| harp IR Ranger (Chapter 20 o | n pp 749 – 758; and curve fittir | · L | Ob | |
| harp IR Ranger (<i>Chapter 20</i> or Readings of a <u>Large</u> | n pp 749 – 758; and curve fittir | ng on pp 771 – 774) Readings of a | Obj ances and Look-Angles | |
| harp IR Ranger (<i>Chapter 20</i> or Readings of a <u>Large</u> | n pp 749 – 758; and curve fittir , Flat, Opaque Object | ng on pp 771 – 774) Readings of a | ances and Look-Angles | |
| harp IR Ranger (<i>Chapter 20</i> or Readings of a <u>Large</u> at Various Distance | n pp 749 – 758; and curve fittir , Flat, Opaque Object les and Look-Angles Look-Angle | ng on pp 771 – 774) Readings of a at Various Dist | ances and Look-Angles Look-Angle | |
| Readings of a Large at Various Distance (Range: 6-80cm) | n pp 749 – 758; and curve fitting, Flat, Opaque Object less and Look-Angles Look-Angle 0°: (Direct) | Readings of aat Various Dist | Look-Angle Company (Direct) | |
| Readings of a Large at Various Distance (Range: 6-80cm) Near: (cm) | n pp 749 – 758; and curve fitting, Flat, Opaque Object res and Look-Angles Look-Angle 0°: (Direct) 15°: (Small Angle) | Readings of a at Various Dist Distance (Range: 6-80cm) | Look-Angle | |

| Distance (Ra | Various Distances and | <u>paque</u> Objec Look-Angles | \ / | Readir | | rious Distance | s and Look | | Objec |
|---------------------------------|-----------------------|-----------------------------------|--------------------------------------------|-----------|-------------|----------------|--------------|-----------------------------|--------|
| ` | ange: 2-400cm) | Look-Ang | gle | Dis | tance (Rang | e: 2-400cm) | | Look-Angle | |
| Near: | | 0°: (Direct) | | Near: (c | | | | | |
| | | : (Si | | | | cm) | | (Small A | \ngle\ |
| | | : (SI | | | | cm) | | (Sindin / | |
| | | : (IV : (La | | - | | (∞ cm) | | (Nild Ai | |
| | (35 cm) | (Lc | ange Angle) | | | (55 Citi) | | (Large 7 | |
| i tch (SPST) (<i>Cl</i> | Using External Resi | stor or VDB | Using Internal Switch open: Switch closed: | | esistor | 1 | osed) with a | eck state of a DMM on th | |
| | | | bend: m" bend: | | | end: | | | |
| | | "Big" bei | nd: | | "Big" ber | d: | | | |
| B/Force (Cha | apter 21 on page 797) | | | | | | | | |
| by Force (cha | | | | | | | ! | | |
| | "Small" force: _ | | "Medium" force: | | "Big" | force: | | | |

| Cold temperature: | (raw) | (K) | (° C) | (° F) |
|------------------------|-------|-----|-------|-------|
| Cool temperature: | (raw) | (K) | (° C) | (° F) |
| Ambient temperature: _ | (raw) | (K) | (° C) | (° F) |
| Warm temperature: | (raw) | (K) | (° C) | (° F) |
| High temperature: | (raw) | (K) | (° C) | (° F) |

• Whisker (Bumper) Switch Using Internal Pull-up Resistor (Chapter 22 on pp 866 – 868)

| Left & Right Whisker | | | | | | |
|----------------------|----------------|--|--|--|--|--|
| Switch open: | Switch closed: | | | | | |

Some Other Sensors Mentioned in the Textbook

- Color (Chapter 21 on page 787)
- Humidity (Chapter 21 on page 787)
- Microphone (Chapter 21 on page 787)

Some of the Sensors **NOT** *Mentioned* in the Textbook

- Battery-Level Meter/Voltmeter
- Carbon Monoxide (CO)
- Compass
- Conductivity
- Electric Current
- Frequency of Sound
- GPS
- IR Remote Board
- Tilt Switch (Mercury Switch)
- Turbidity
- Vision (Pixicam)